Design and Evaluation of a Single-Phase Modular Multilevel Inverter

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Abstract: - This work shows the design and implementation of a cascaded single-phase modular multi-level inverter with asymmetric topology. The output of the inverter can be adjusted to 7, 15 and 31 voltage levels using a step modulation. The selective harmonic elimination (SHE) technique is used to determine the switching angles of the mosfet. The results were simulated in MATLAB and verified by the implementation of the inverter, evaluating its performance using the total harmonic distortion (THD).

Keywords— Multilevel inverter, SHE, step modulation, THD, MATLAB.

1 Introduction

Multilevel power inverters are a novel technology that has emerged as an alternative to traditional twolevel inverters [1]. These inverters allow you to convert the electrical energy provided by direct current sources, such as batteries or solar panel banks, into an ideal alternating current of sine wave form whose parameters (amplitude, frequency) can be fixed or variable. The general concept [2] involves a high number of switches based on power semiconductors that develop the conversion at several progressive levels, achieving very low harmonic content depending on the number of levels of the inverter.

The first work related to conversion into multiple steps or voltage levels was patented in 1975 [3]. Subsequently, in 1980 a variant of multilevel inverter was patented [3], to which clamping diodes were added. The *Flying Capacitor Multilevel Inverter* was introduced in the mid-1990s [4], [5]. This topology offered several advantages over the NPC (*Neutral Point Clamped*) inverter, as is clearly stated in [6]. The cascade multilevel inverter with separate DC sources was patented in 1997 [7].

Since the first works in multi-level inverters, important advances have been made that have allowed the development and application of this technology. Among the most relevant publications can be cited [6] and [8], where a review of the state of the art of multilevel inverters is carried out. On the other hand, in [9] is presented a very interesting work that addresses the topic of the simulation of multilevel inverters. Another significant contribution has been made by master's degrees and doctoral theses focused on multilevel inverters, within which they are cited [10-13]. Recently research has been carried out focused on the improvement of particular parameters of the multilevel inverter. For example, new topologies such as those proposed in [16] and [17], as well as the use of heuristic optimization techniques applied in the modulation of the switching signals [18] - [21].

The parameter selected to measure the performance of the inverter is the total harmonic distortion factor or THD, which is a measure of the quality of the output voltage waveform [22] - [25].

2 Multilevel inverters

Multilevel conversion

Multilevel power conversion was first introduced in the early 1980s. The general concept involves the use of a large number of semiconductor switching devices to develop the conversion into small steps or voltage levels. Figure 1 shows a schematic diagram of a single-phase inverter with different number of levels:

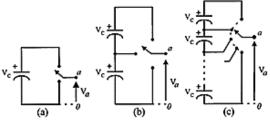


Fig. 1. Single-phase inverter (a) two-levels, (b) three-levels, (c) *m* levels.

As can be seen in Fig. 2, in a multilevel inverter it is desired to synthesize a waveform similar to a sine signal, in which, depending on the number of available DC sources, the distortion will be much lower [26]. Among its main advantages we can mention [6]:

- The multilevel input voltage arrangement allows the input voltage to be increased several times using the same switches as a conventional inverter.
- The power of the inverters is increased by using higher voltages, without the need to increase the electrical current, thus avoiding greater losses during the current conduction, and consequently, to improve the inverter performance.

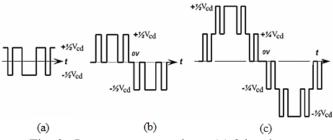


Fig. 2. Inverter output voltage (a) 2 levels, (b) 3 levels, (c) 5 levels.

Topologies

There are three main topologies of multilevel inverter:

- Diode clamped inverter.
- Capacitor clamped inverter.
- Cascaded multilevel inverter.

Other hybrid topologies based on previous topologies have been introduced [6]:

- Hybrid asymmetric multilevel inverter.
- H-Bridges cascaded inverter and CD-CD sources with insulation.
- Cascaded multilevel inverter topology.
- Inverter with Soft Switching.
- 3 level booster rectifier / matrix inverter.
- Inverter coupled by transformer.

Cascaded multilevel inverters

This topology is based on the serial connection of single-phase inverters with separate CD power supplies. Fig. 3 shows the power circuit for a branch of a nine-level inverter with four H-bridges (modules) per phase [6].

Hybrid asymmetric multilevel inverter

The main difference of this inverter with the previous one is that it is symmetrical, because the DC voltage sources used are of different value, which raises the number of levels at the output of the inverter using the same number of sources.

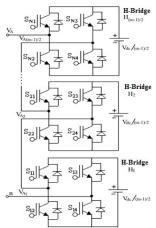


Fig. 3. Three H-bridges (stages) multilevel cascaded inverter.

In fig. 4 the typical switching waveforms for a multilevel inverter of separate CD sources can be seen.

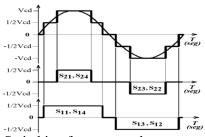


Fig. 4. Switching for separated sources and the voltage output waveform.

This number of levels can be increased with a different switching sequence.

Table I shows the levels that can be obtained in an asymmetric inverter versus a symmetric inverter with 2, 3, 4 and 5 H-bridges or stages.

TABLE I. STAGES AND LEVELS UPON THE TYPE OF MULTILEVEL INVERTER

numbers	Number of levels		
of H- Bridges (Stages)	Symmetrical inverter	Asymmetric inverter	
2	5	7	
3	7	15	
4	9	31	
5	11	63	

It should be noted that in Table I, the voltage sources that are added in the case of the asymmetric inverter are half the value of the previous one. The number of levels can be increased by choosing voltage ratios between independent sources other than proportional ratio [14].

3 Step modulation

The main objectives of the strategies switching DC / AC are, besides regulating the output amplitude and frequency, is the minimization of the total harmonic content of the output voltage of the inverter and the balance of the instantaneous voltage inverter capabilities [27], [28].

The most commonly used technique in multi-level inverters is switching in steps. This aims to synthesize a step waveform very similar to a sine waveform with low harmonic content. This type of output can be seen in Fig. 6 for an 11-level inverter.

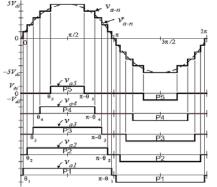


Fig. 5. Generation of a step waveform from individual levels.

The Fourier series of a step waveform can be obtained by adding the individual levels, as shown in Fig. 6.

The output voltage of this step waveform can then be expressed as [15]:

$$v_{out} = \sum_{n=1}^{\infty} \frac{4V_{CD}}{n\pi} \left[\sum_{k=1}^{s} \cos(n\theta_k) \right] \sin(n\omega t)$$
(1)

Where:

n is the odd harmonic order (1, 3, 5, 7, 9...)*s* is the number of stages of the inverter. *k* is a positive integer (1, 2, 3, 4, 5...s)

 θ_k is the k^{th} switching angle, which must satisfy: $\theta_1 < \theta_2 < \theta_s < \pi/2$

From (1), the amplitude of the odd harmonics, including the fundamental component can be expressed as:

$$a_n = \frac{4V_{CD}}{n\pi} \sum_{k=1}^s \cos\left(n\theta_k\right) \tag{2}$$

Expanding the above equation gives:

$$a_n = \frac{4V_{CD}}{n\pi} \Big[\cos(n\theta_1) + \cos(n\theta_2) + \dots + \cos(n\theta_s) \Big]$$
(3)

The conduction angles $\{\theta_1, \theta_2, \theta_3, \dots, \theta_s\}$ can be selected such that the total harmonic distortion of the output voltage can be minimized.

For example, it is desired to control the peak value of the output voltage, a_1 , in a 3-stage inverter with 7 voltage levels. In addition to eliminating the odd harmonic components (i.e. 5th and 7th) then equation (3) can be written as:

$$\begin{bmatrix} \cos(\theta_1) + \cos(\theta_2) + \cos(\theta_3) \end{bmatrix} = m$$

$$\begin{bmatrix} \cos(5\theta_1) + \cos(5\theta_2) + \cos(5\theta_3) \end{bmatrix} = 0$$

$$\begin{bmatrix} \cos(7\theta_1) + \cos(7\theta_2) + \cos(7\theta_3) \end{bmatrix} = 0$$
Where:
$$m = \frac{\pi V_1}{4V_{CD}}$$
(5)

The expansion of the Fourier series as described by (4) generates a transcendent (non-linear) equation and to solve it special methods are required, such as Newton-Raphson [29]. However, the Matlab[®] computational tool allows to obtain the solution of the system of nonlinear equations as (4) by using the *fsolve* function. These switching angles must be converted into time values for the implementation of the control algorithm in the digital device. It should also be noted that from these angles the other switching angles can easily be obtained by taking advantage of the quarter-wave symmetry of the desired output signal.

4 Multilevel inverter simulation

For the simulation of the inverter a model was created in Simulink[®], based on the H-bridge scheme as in fig. 8. From which a multi-level inverter can be obtained by cascading each stage.

The algorithm was developed in Matlab[®] to facilitate the solution of the system of transcendent equations described in (4) and to obtain the appropriate switching angles. These angles are converted into time units and adjusted to the switching scheme of the asymmetric inverter.

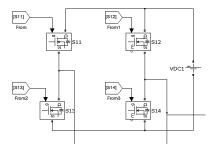


Fig. 6. Simulation model for a single inverter stage (H-bridge).

To evaluate the quality of the output voltage waveform obtained, the total harmonic distortion factor (THD) was used [26]. The THD is mathematically defined as:

$$THD(\%) = \frac{1}{a_1} \sqrt{\sum_{n=3}^{\infty} (a_n^2) \cdot 100\%}$$
(6)

Where:

 a_1 is the amplitude of the fundamental harmonic. a_n is the amplitude of the n^{th} odd harmonic.

The inverter output voltage waveform must comply with international regulations that establish a THD of less than 5%. For practical purposes, expression (6) was used. The desired parameters of the output waveform of the inverter are: Amplitude of the fundamental component: 169.7V, output frequency: 60Hz, THD <5%.Figures 9 to 11 show the output waveform and the harmonic spectra corresponding to an asymmetrical single-phase multilevel inverter for a number N of stages (H-Bridges) equal to 2, 3 and 4 respectively, in the case of a purely resistive load.

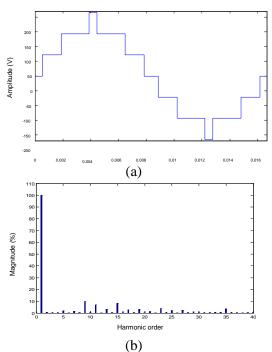
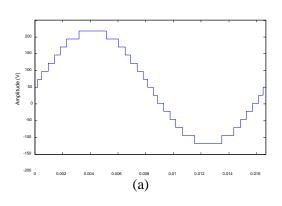


Fig. 7. (a) Voltage output waveform of the asymmetric inverter with N=2, (b) harmonic spectrum.



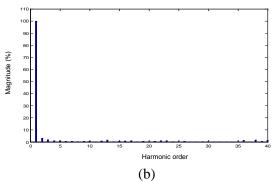


Fig. 8. (a). Voltage output waveform of the asymmetric inverter with N=3, (b) harmonic spectrum.

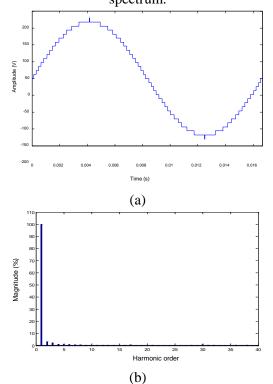


Fig. 9. (a) Voltage output waveform of the asymmetric inverter with N=4, (b) harmonic spectrum.

5 Prototype setup

In order to verify the results of the simulations, a prototype of the modular multilevel inverter was developed, in which the number of stages (H-bridges) can be varied from two to four [27].

Each module of the inverter is primary formed by isolation and conditioning stage, and the associated power electronics. IRF840 mosfet devices were used for each power stage [28].

The signal conditioning was carried out using the IR2110 chip which performs the appropriate switching and applies it to each mosfet gate.

Isolation was performed with 4N25 optocouplers. The generation of the switching sequence was performed using a PIC18F4550.

Experimental setup

In order to evaluate the performance of the multilevel inverter, experimental tests with purely resistive load were carried out. The output waveforms were measured with an Agilent DSO3202A type oscilloscope. The data were then taken to a Personal Computer where the THD value and the harmonics spectrum were calculated. Fig. 12 shows a block diagram of the experimental setup.



Fig. 10. Experimental setup.

Fig. 11 shows the output waveform of the 2-stage (H-bridge) and 7-level inverter, also to its harmonic profile.

Figures 11 to 13 show the output waveform and the harmonic profile corresponding to the asymmetrical single-phase multilevel inverter for a N number of stages equal to 2, 3 and 4 respectively (7, 15 and 31 levels). It is important to note how the measured output waveforms are almost identical to those previously obtained by simulation.

Table III shows the results of the experimental tests. It can be seen that the 4-stage asymmetric multilevel inverter (31 levels) allows to obtain a THD <5% satisfying the IEEE-519 standard [25]. While the 3-stage inverter provides a THD quite close to the desired value, which could be improved by a waveform filtering operation. In all cases an RMS voltage value of the fundamental component was obtained very close to the desired value of 120 Vrms.

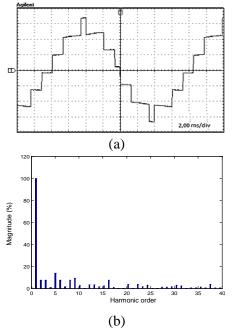


Fig. 11. (a) Voltage output waveform of the symmetric inverter with N=2, (b) harmonic spectrum.

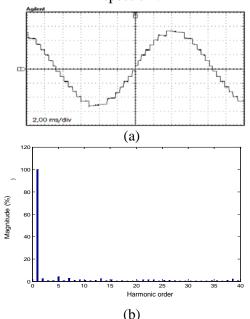
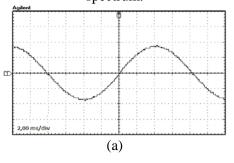


Fig. 12. (a) Voltage output waveform of the symmetric inverter with N=3, (b) harmonic spectrum.



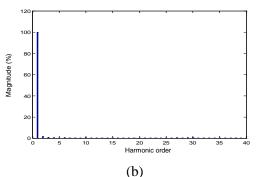


Fig. 13. (a) Voltage output waveform of the symmetric inverter with N=4, (b) harmonic spectrum.

TABLE III CASCADE ASYMMETRIC MULTILEVEL INVERTER

Number of stages (N)	Numbe r of levels	DC sources (volts)	Output RMS voltage (V)	TH D
2	7	72V, 144V	121.00	17.4
				0
3	15	24V, 48V, 96V	122.70	6.27
4	31	12V, 24V,	120.84	2.17
		48V,96V		

6 Conclusions

The asymmetric multilevel inverter in cascade of 4 stages (31 levels) allows to obtain an output waveform of very low harmonic content and that satisfies the international regulations in force (IEEE-519) with a THD inferior with more than 5% allowed.

The experimental implementation, through the development of a prototype of the inverter, allowed to verify the simulation results by means of measurements, with a slight difference in the results, mainly because the switching delay times of the semiconductor devices involved and due to the switching losses were not taken into account in the model.

Finally, it is recommended the use of evolutionary optimization techniques that allow solving the proposed optimization problem, without the need to use complex classical techniques to obtain the solution of the system of transcendental equations. References:

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